

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV1164B

SIMOTICS GP - 160 L - IM B5 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data

Safe Area

U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	η ³⁾			$\cos\phi$ ³⁾			I_A/I_N I_f/I_N	M_A/M_N T_f/T_N	M_K/M_N T_B/T_N	IE-CL
								4/4	3/4	2/4	4/4	3/4	2/4				
400	Δ	50	15.00	-/-	30.00	1460	98.0	88.7	89.0	87.8	0.82	0.76	0.63	7.5	3.0	3.6	IE1
690	Y	50	15.00	-/-	17.30	1460	98.0	88.7	89.0	87.8	0.82	0.76	0.63	7.5	3.0	3.6	IE1
460	Δ	60	17.30	-/-	28.50	1755	94.0	90.5	90.9	89.8	0.84	0.79	0.68	8.0	2.9	3.6	IE1

IM B5 / IM 3001 FS 160 L IP55 IEC/EN 60034 IEC, DIN, ISO, VDE, EN
 Environmental conditions : -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold) : 6.88 s | 14 s

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	65 / 77 dB(A) ²⁾	69 / 81 dB(A) ²⁾	Vibration severity grade	A
Moment of inertia	0.0560 kg m ²		Insulation	155(F) to 130(B)
Bearing DE NDE	6209 2Z C3	6209 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} , F _{Rad} , min 50 60Hz ¹⁾ for coupling operation	40000 h	32000 h	Frame material	aluminum
Lubricants	Unirex N3		Net weight of the motor (IM B3)	73 kg
Regreasing device	No		Coating (paint finish)	Standard paint finish C2
Grease nipple	-/-		Color, paint shade	RAL7030
Type of bearing	Locating bearing NDE		Motor protection	(A) without (Standard)
Condensate drainage holes	No		Method of cooling	IC411 - self ventilated, surface cooled
External earthing terminal	No			

Terminal box

Terminal box position	top	Max. cross-sectional area	16 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	19 mm - 28 mm
Type of terminal box	TB1 J00	Cable entry	2xM40x1,5
Contact screw thread	M5	Cable gland	2 plugs

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Notes:
 I_A/I_N = locked rotor current / current nominal 1) L10mh according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411
 M_A/M_N = locked rotor torque / torque nominal 2) at rated power / at full load
 M_K/M_N = break down torque / nominal torque

responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.
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